Rate Coding and Signal Processing

4 Fabrizio Gabbiani

5 Introduction

2

3

6 In the peripheral and central nervous system, many neurons encode 7 information and pass it on to other neurons by generating irregular 8 sequences of short voltage pulses, typically less than 1 ms in du-9 ration, called action potentials. The shape of these action potentials, 10 or spikes, is usually quite stereotyped over the course of time. The 11 sequence of spike occurrence times generated by the cell, often 12 called the spike train, is therefore thought to carry most of the 13 information that a neuron communicates to its targets. When study-14 ing how sensory information might be encoded in neuronal spike 15 trains, one is faced with the fact that spike trains are often quite 16 variable under seemingly identical stimulation conditions (Figure 17 1). Is this variability simply noise, perhaps due to uncontrolled 18 changes in the state of some internal variable, or does it carry 19 information about the stimulus? Answering this question in a par-20 ticular case would require a thorough knowledge of the biophysical 21 mechanisms of spike generation and of stimulus coding-22 knowledge that is out of reach at present.

Although no universal definition exists, the term *rate coding* is
applied in situations where the precise timing of spikes is not
thought to play a significant role in carrying sensory information.
Rate codes have been identified in many sensory systems and are
probably the best understood means by which neurons encode information. In many cases, rate codes have been shown to play an
important role in determining behavioral responses of animals.

30 Rate coding comes in two flavors: mean firing rate codes and 31 instantaneous firing rate codes. The sensory information conveyed 32 by these two types of codes can be studied rigorously by applying 33 classical methods of statistical signal processing borrowed from 34 the engineering literature. In the next two sections, we will show 35 how these methods can be carried over to the analysis of neuronal 36 spike trains. Before turning to more general examples in the third 37 section, we will illustrate them in the case of electrical field 38 amplitude-sensitive neurons of weakly electric fishes. These ani-39 mals possess an unusual sense for the electrical properties of their 40 environment that is favorable to computational investigations (see 41 ELECTROLOCATION).

42 Rate coding is not the only mean by which neurons convey in-43 formation. In weakly electric fishes and in other auditory-like sen-44 sory systems, the role played by spike timing information is well 45 documented (see ELECTROLOCATION and ECHOLOCATION: COCH-46 LEOTOPIC AND COMPUTATIONAL MAPS). Two articles address the 47 issue of spike timing in cortical circuits (SYNFIRE CHAINS; SYN-48 CHRONIZATION: BINDING AND EXPECTANCY). Finally, the role of 49 rate coding in the context of neuronal populations is examined in 50 POPULATION CODES and MOTOR CORTEX, CODING AND DECODING 51 OF DIRECTIONAL OPERATIONS.

52 Mean Firing Rate Coding

53 An increase in firing rate is typically the most conspicuous change 54 recorded from sensory neurons in response to external stimuli. It 55 is therefore natural to ask how well the spike count observed in a 56 single trial from such a cell can predict the presence of the stimulus. 57 Let us take the example of a neuron having a mean spontaneous 58 rate $\bar{\lambda}_0 = 30$ spk/s that fires at a rate of $\bar{\lambda}_s = 50$ spk/s under 59 stimulus presentation (Figure 1B). We will first assume for sim-60 plicity that spikes are generated completely independently of each 61 other (i.e., following a Poisson process) and thus do not carry any 62 additional information beyond their mean rate of occurrence.

Figure 2A illustrates the distribution of spike counts observed
during a 200 ms window in the baseline and stimulus condition for
this model neuron. The overlap between these two distributions
indicates that guessing the presence of the stimulus from the spike

(1)

67 count observed in a single trial will lead to a significant fraction of 68 errors. A simple method to decide between the two alternatives 69 "stimulus present" or "no stimulus" consists in choosing a thresh-70 old number of spikes, k_{thres} , and classifying the observed responses, 71 n, as baseline activity or stimulus-induced activity according to whether the threshold is exceeded or not: 72

73

74

 $n < k_{\text{thres}} \Rightarrow$ baseline activity $n > k_{\text{thres}} \Rightarrow \text{stimulus present}$

75 This decision strategy leads to two types of errors. On the one 76 hand, we might call for the stimulus to be present in a trial during 77 which spontaneous activity was unusually high. This type of error 78 is called a false alarm. On the other hand, we might confuse an 79 unusually low stimulus response with spontaneous activity, an error 80 called a false miss. Clearly, the proportion of false alarms to false 81 misses depends on the choice of the threshold k_{thres} : high (low) 82 threshold values correspond to low (high) probabilities of false 83 alarms with higher (lower) fractions of false misses. It is customary 84 to characterize the performance of this detection algorithm by vary-85 ing the threshold from low to high values and plotting the proba-86 bility of correct detection, p_D (i.e., 1 minus the probability of false 87 misses), as a function of the probability of false alarms, p_{FA} (i.e., 88 1 minus the probability of correct rejections; Figure 2B).

89 This curve is called the receiver operating characteristic (ROC) 90 curve of the detection algorithm (a term originating from early 91 applications to radar observations). The dashed diagonal line $p_D =$ 92 p_{FA} corresponds to chance performance (i.e., independent of the 93 threshold, k_{thres} , the probability, p_D , of correctly detecting the stim-94 ulus is as good as the probability, p_{FA} , of incorrectly mistaking 95 spontaneous activity with stimulus-induced activity). Thus, the 96 higher the ROC curve lies above the diagonal, the better the per-97 formance of our detection algorithm and, in the limit of perfect 98 performance, $p_D = 1$ over the entire interval $0 \le p_{FA} \le 1$.

99 From the ROC curve, one can obtain the values of p_{FA} and 100 $p_D(p_{FA})$ that minimize the overall probability of stimulus detection 101 error (comprising both false alarms and false misses). If the stim-102 ulus is presented on average in one-half of the trials, the error rate 103 is given, for a fixed value of p_{FA} , by

 $\varepsilon(p_{FA}) = \frac{1}{2} p_{FA} + \frac{1}{2} (1 - p_D(p_{FA}))$ (2)105 106 The minimum of $\varepsilon(p_{FA})$ as a function of p_{FA} can be easily found by numerical methods (see Figure 2C). The corresponding thresh-

107 108 old k_{thres} may then be obtained from $p_{FA}(k_{\text{thres}})$. Thus, in our example the minimal error rate $\varepsilon = 0.24$ is achieved for $p_{FA} = 0.26$, 109 corresponding to a detection threshold k_{thres} of 8.5 spk/s. 110 111 One important question remains: Given the simplicity of this

112 algorithm, could it be outperformed by a more sophisticated one? 113 Remarkably, this is not the case: under fairly general assumptions, 114 the threshold condition of Equation 1 is equivalent to a similar 115 condition on the likelihood ratio, $l(n) = p_s(n)/p_0(n)$, where $p_s(\cdot)$ 116 and $p_0(\cdot)$ are the probability distributions of the spike count in the presence and absence of the stimulus, respectively (Figure 2A). The 117 118 likelihood ratio is a quantity central to signal detection theory, and 119 this equivalence shows that, for a fixed value of p_{FA} , no other al-120 gorithm taking into account only the probability distributions of 121 Figure 2A can outperform the threshold test. Thus, the ROC curve 122 defines the performance of an ideal observer of the mean rate code, 123 having complete access to $p_0(\cdot)$ and $p_s(\cdot)$. Whether neurons or neu-124 ronal networks in the brain adopt similar algorithms to read out 125 information about the external world remains an open question.

126 The performance of the ideal observer algorithm will be affected 127 by at least two additional factors, the first being the length of the 128 time window over which spikes are registered. Longer windows 129 typically lead to better performance by averaging out the noise 130 component of the spike rate that causes deviations from the mean. 131 In the case of the Poisson process discussed above, for a fixed mean 132 firing rate $\bar{\lambda}$, the mean number of spikes observed in a time window T is given by $\bar{n} = \bar{\lambda}T$, whereas the standard deviation is $\sigma = \sqrt{\bar{\lambda}T}$. Thus, $\bar{n}/\sigma \propto \sqrt{T}$, and the signal grows as \sqrt{T} with respect to 133 134 noise over the course of time. Currently, the time interval that is 135 136 relevant for behavioral responses often is only weakly constrained **137** by experimental observations.

138 The second factor is the regularity of the spike train or, in other 139 words, the amount of noise that is present to start with. While many 140 neurons in cortical areas have highly variable responses resembling 141 those obtained from Poisson processes, other neurons can be much 142 more regular. In the weakly electric fish Apteronotus, for example, 143 the spike trains of primary sensory afferent neurons sensitive to 144 amplitude modulations of the electrical field have a variability that 145 is almost an order of magnitude smaller than that expected from a 146 Poisson spike train on behaviorally relevant time scales (Ratnam 147 and Nelson, 2000). These neurons are thought to encode informa-148 tion necessary for the detection of small prey, such as the water 149 fleas on which the fish feeds. Computer simulations, behavioral 150 observations, and electrophysiological recordings suggest that the 151 firing rate of these cells will increase by only a few spikes per 152 second during the 200 ms needed to detect the prey. An ROC 153 analysis reveals that increases of 2-3 spk/s above baseline activity 154 can be detected with greater than 90% accuracy even if the prob-155 ability of a false alarm is very low, 0.1% (Figure 2D). Such low 156 false alarm rates ($p_{FA} \leq 0.001$) are constrained from behavioral 157 observations showing that fishes almost never strike a nonexistent 158 prey. As illustrated in Figure 2D, three spike trains of models de-159 signed to reproduce the short-term variability of the experimental 160 spike trains cannot reproduce these results. The first model 161 (squares) reproduces only the mean firing rate of the afferents, 162 while the second and third models also reproduce the interspike 163 interval distribution (diamonds) or the joint statistical distribution 164 of two successive interspike intervals (triangles), respectively. The 165 regularity and statistical structure of the spike trains over at least 166 three firing cycles is therefore responsible for this unusually low

167 detection threshold.

188

203

168 Instantaneous Rate Coding

169 Stimuli that vary on a fast time scale-comparable to the 200 ms 170 observation window introduced in the last section-cannot be en-171 coded by the mean spike count alone. Such stimuli are ubiquitous 172 in the sensory environment of many animals. Motion of an object 173 or self-motion, for example, result in rapid changes in light inten-174 sity across the visual field. Sound stimuli used for communication 175 or localization correspond to rapidly varying changes in air pres-176 sure. In the case of weakly electric fishes considered in the last 177 section, time-varying electrical field amplitude modulations occur 178 as the fish moves through an electrically dense environment in 179 water.

180 Such time-varying stimuli could be encoded by time-varying 181 changes in the instantaneous firing rate of a neuron, even if the 182 precise timing of spikes does not play an essential role in the pro-183 cess (Gabbiani and Koch, 1999). Consider, for example, the Pois-184 son spike train model of the previous section with a spontaneous 185 rate $\bar{\lambda} = 30$ spk/s. We assume that changes in the instantaneous 186 firing rate from its mean value, $\overline{\lambda}$, are caused by changes of the 187 stimulus, s(t), from its mean value, \bar{s} ,

$$\lambda(t) = \alpha(s(t) - \bar{s}) + \bar{\lambda} \tag{3}$$

190 The constant α is a conversion factor between stimulus and firing 191 rate, and $\lambda(t)$ is assumed to be positive. In the following discussion 192 the stimulus will usually be assumed to have zero mean, i.e., $\bar{s} = 0$. 193 How much information does such a spike train convey about the 194 stimulus? Using an approach analogous to that introduced in the 195 last section, this question can be addressed by presenting a random 196 stimulus s(t) and estimating it from the spike train (Figure 3A). 197 Because s(t) varies randomly in time, the estimate $s_{est}(t)$ will also 198 have to vary in time to track s(t). Thus, this estimation problem is 199 more complex than the detection problem considered in the last 200 section. It is customary to minimize the root mean square error 201 between the stimulus and its estimate,

$$\varepsilon = \langle (s(t) - s_{\text{est}}(t))^2 \rangle^{1/2} \tag{4}$$

where the average is taken over the stimulus presentation interval (Figure 3*A*). It is much more difficult to find an optimal estimate $s_{est}(t)$ from the spike train than it is to find an optimal classification strategy based on the spike count. A simplification is therefore

- 208 made by looking only at estimates obtained from linear superpos-
- itions of a waveform, h(t), around each spike. If $r(t) = \sum_i \delta(t t_i)$
- 210 is a sum of delta functions representing the sequence of spikes at
- **211** times $\{t_i\}$, the estimated stimulus is assumed to be of the form

212
$$s_{est}(h, t) = \int h(t - t_0)r(t_0)dt_0 - \bar{r} \int h(t_0)dt_0$$

= $\sum_i h(t - t_i) - \bar{r} \int h(t_0)dt_0$ (5)

214 where \bar{r} is the mean firing rate of the cell and the second term 215 ensures that $s_{est}(t)$ has zero mean value, as was assumed for s(t)216 (Figure 3B). Under this assumption, the optimal waveform, h(t), 217 minimizing the root mean square error in Equation 4 can be ob-218 tained by standard statistical and Fourier transform techniques. The 219 minimum value obtained for the root mean square error, ε , is usu-220 ally normalized by the stimulus standard deviation, σ , which cor-221 responds to chance guessing (i.e., to the error obtained in Equation 222 4 when $s_{est}(t) = \bar{s} = 0$). Figure 3C illustrates the result of this 223 estimation procedure using the spike train of an amplitude-sensitive 224 afferent obtained in response to a random electrical field amplitude 225 modulation in a second species of weakly electric fishes, Eigen-226 mannia. From the spike train, the amplitude modulation could be 227 estimated with an error $\varepsilon/\sigma = 0.17$. Equivalently, our ideal linear 228 observer could reproduce 83% of the stimulus standard deviation 229 using a single spike train.

230 In contrast, estimation of the same stimulus using a spike train 231 generated using a Poisson process and Equation 3 is considerably 232 less accurate (only 25% of the stimulus standard deviation is recovered; Figure 3D), because a Poisson process is more variable 233 234 than the spiking of *Eigenmannia* afferents (Kreiman et al., 2000). 235 Thus, as in the signal detection case, spike train variability plays 236 an important role in stimulus estimation. Other factors that play a 237 significant role in the encoding capacity of the instantaneous firing 238 rate are the contrast of the stimulus (or its standard deviation σ ; 239 typically, higher contrasts result in larger firing rate modulations 240 and thus better encoding), the mean firing rate of the cell (higher 241 mean firing rates lead to a finer temporal sampling of the stimulus), 242 and the cutoff frequency of the stimulus (accurate encoding is pos-243 sible only when temporal stimulus frequencies are well below the 244 mean firing rate of the cell).

245 The assumption relating spike train and stimulus estimate by a 246 linear transform embodied in Equation 5 works very well in prac-247 tice when the encoding of the stimulus by the spike train can be 248 described by equations analogous to Equation 3. This result can be 249 justified theoretically (Gabbiani and Koch, 1999). In contrast, no 250 systematic studies have been carried out on the effect of nonlinear 251 relations between stimulus and firing rate; only a few scattered 252 examples have been examined (Gabbiani and Koch, 1999; Haag 253 and Borst, 1998).

254 Rate Coding in Neural Systems

Instantaneous and mean firing rate codes have been extensively
characterized in a variety of different neuronal systems. In the following discussion, we will highlight a few directions of investigation and some open questions relevant to the subject.

259 Starting in the late 1940s, signal detection methods have been 260 applied to characterize the information conveyed by neuronal spike 261 trains, along the lines prescribed earlier in this article (see Parker 262 and Newsome, 1998). The investigation of neuronal signals carried 263 by optic nerve fibers of the horseshoe crab Limulus was one of the 264 earliest examples of work on this topic (see Parker and Newsome, 265 1998). Over the next 30 years, signal detection methods were ex-266 tended to the activity of sensory neurons in the early auditory, 267 somatosensory, and visual pathways of vertebrates. The variability 268 of retinal ganglion cell spike trains, for example, has been exten-269 sively investigated in an attempt to explain its impact on the en-270 coding reliability of visual signals (Parker and Newsome, 1998).

More recently, signal detection methods have been applied to
neurons in cerebral cortical areas (visual and somatosensory, for
instance) of monkeys trained to perform discrimination tasks. In
some cases, the reliability of neuronal firing could be compared to

275 the behavioral accuracy of the animal performing the task. These 276 results, together with analyses of variability and correlation across 277 cells, have led to neural models of signal encoding that can account 278 for the animal's behavior (see Parker and Newsome, 1998). The 279 neural mechanisms underlying behavioral selection in those dis-280 crimination tasks, however, remain difficult to test experimentally.

281 In the cockroach, directional escape responses to wind stimuli 282 are thought to rely on the mean firing rate of 14 giant interneurons 283 (GIs). Several models that could in principle explain escape be-284 haviors on the basis of the mean firing rate of GIs have been tested 285 by directly manipulating them through current injections (Levi and 286 Camhi, 2000). The results of these experiments suggest that a di-287 rectional average of the GIs' mean firing rate is the most accurate 288 description of the behavior. Mean firing rate codes across popula-289 tion of neurons have also been shown to play similar roles in ver-290 tebrate neurons, in the generation of visual saccades in the superior 291 colliculus of monkeys, and in the generation of limb movements 292 in motor cortical areas (Sparks, Kristan, and Shaw, 1997).

293 Given that in the engineering literature signal estimation is usu-294 ally considered a close relative of signal detection (Poor, 1994), it 295 is perhaps surprising that it has been applied to neural spike trains 296 only within the past 10 years. Estimation of time-varying stimuli 297 along the lines developed earlier in this article has shown that single 298 spike trains of sensory neurons can accurately convey information 299 about time-varying stimuli, although the results are usually less 300 spectacular than those shown in Figure 3B (Borst and Theunissen, 301 1999). At present, these methods have been applied mainly to in-302 vertebrate and lower vertebrate preparations. Mechanisms of en-303 coding across multiple neurons and their relation to behavior have 304 received little attention so far (but see Stanley, Li, and Dan, 1999). 305 In contrast, instantaneous firing rate codes have been extensively 306 studied by characterizing how stimulus attributes are encoded in 307 the instantaneous firing rate of neurons through generalizations of 308 Equation 3. Such models are particularly well developed for the 309 early visual pathways of mammals, from the retina to early visual 310 cortical areas (Dayan and Abbott, 2001).

311 Discussion

312 Mean and instantaneous firing rate codes are undoubtedly the best 313 documented and best understood way by which neurons transmit 314 information. Several other codes have also been studied, among 315 them the mechanisms of coincidence detection in auditory pro-316 cessing (Pena and Konishi, 2001). More elaborate coding schemes are likely to be found, particularly across populations of neurons, 317 318 although the highly sophisticated codes at the heart of information 319 theory seem unlikely to find a place in describing the signaling 320 repertoire of sensory and motor neurons. 321 One question that has long intriguied neuroscientists is whether

322 the spike train variability usually observed in neurons using rate 323 coding also carries further sensory information (Bullock, 1970). 324 This question is difficult to answer rigorously. In the case of the 325 cockroach, the pattern of spikes in GIs does not appear to play a 326 role in determining escape behaviors (Liebenthal, Uhlmann, and 327 Camhi, 1994). On the other hand, it has been suggested that in 328 electric fishes, coincidence detection could be used to integrate the 329 information conveyed by the amplitude-sensitive receptors de-330 scribed in this article and in Berman and Maler (1999). Thus, neu-331 rons might use a combination of different codes simultaneously at 332 different levels of a neuronal circuit.

- 333 Roadmap: Neural Coding
- 334 Related Reading: Population Codes; Spansory Coding and Information 335 Transmission

336 References

- 337 Borst, A., and Theunissen, F. E., 1999, Information theory and neural cod-338 ing, Nature Neurosci., 2:947–957. ♦
- 339 Berman, N. J., and Maler, L., 1999, Neural architecture of the electrosen-340 sory lateral line lobe: Adaptations for coincidence detection, a sensory 341 searchlight and frequency-dependent adaptive filtering, J. Exp. Biol., 342 202:1243-1253.

- 343 Comp: asterisk becomes diamond symbol at end of entryBullock, T. H.,
- 344 1970, The reliability of neurons, J. Gen. Physiol., 55:565–584. ♦
- Dayan, P., and Abbott, L. F., 2001, *Theoretical Neuroscience*, Cambridge, MA: MIT Press. ◆
- Gabbiani, F., and Koch, C., 1999, Principles of spike train analysis, in Methods in Neuronal Modeling: From Synapses to Networks (C. Koch and I. Segev, Eds.), 2nd ed. Cambridge, MA: MIT Press, pp. 313– 360. ◆
 Haag, J., and Borst, A., 1998, Active membrane properties and signal en-
- Haag, J., and Borst, A., 1998, Active membrane properties and signal encoding in graded potential neurons, J. Neurosci., 18:7972–7986.
- Kreiman, G., Krahe, R., Metzner, W., Koch, C., and Gabbiani, F., 2000,
 Robustness and variability of neuronal coding by amplitude-sensitive afferents in the weakly electric fish *Eigenmannia, J. Neurophysiol.*, 84:189–204.
- **357** Levi, R., and Camhi, J. M., 2000, Population vector coding by the giant interneurons of the cockroach, *J. Neurosci.*, 20:3822–3829.
- Liebenthal E., Uhlmann, O., and Camhi, J. M., 1994, Critical parameters
 of the spike trains in a cell assembly: Coding of turn direction by the
 giant interneurons of the cockroach, J. Comp. Physiol. A, 174:281–296.
- Parker, A. J., and Newsome, W. T., 1998, Sense and the single neuron:
 Probing the physiology of perception, *Annu. Rev. Neurosci.*, 21:227–
 277. ◆
- 365 Pena, J. L., and Konishi, M., 2001, Science, 292:249–252.
- Poor, H. V., 1994, An Introduction to Signal Detection and Estimation, New York: Springer-Verlag. ◆
- Ratnam, R., and Nelson, M. E., 2000, Nonrenewal statistics of electrosensory spike trains: Implications for the detection of weak sensory signals, *J. Neurosci.*, 20:6672–6683.
- Sparks, D. L., Kristan, W. B., and Shaw, B. K., 1997, The role of population coding in the control of movement, in *Neurons, Networks, and Motor Behavior* (P. S. G. Stein, S. Grillner, A. I. Selverston, and D. G. Stuart, Eds.), Cambridge, MA: MIT Press, pp. 21–32. ◆
- Stanley, G. B., Li, F. F., and Dan, Y., 1999, Reconstruction of natural scenes from ensemble responses in the lateral geniculate nucleus, *J. Neurosci.*, 19:8036–8042.



Plate # 0

383 384 385

Figure 1. A, Nine spike trains recorded from an amplitude-sensitive afferent in the weakly electric fish Eigenmannia in response to repeated presentations of the same random electrical field amplitude modulation (shown on top). (Adapted from Kreiman et al., 2001.) B, Ten spike trains (200 ms long) obtained 380 from a Poisson process with mean firing rate $\lambda_0 = 30$ spk/s (spontaneous rate, left) and $\lambda_s = 50$ spk/s (stimulus-induced rate, right).



Figure 2. A, Probability distributions of the spike count observed in a 200 ms window for the two Poisson processes illustrated in Figure 1B. Choosing a threshold number of spikes (k_{thres}) to discriminate between the presence or absence of the stimulus leads to errors because of the overlap of the distributions. The probability of false alarm (p_{FA}) and of correct detection (p_D) are illustrated by the gray and hatched areas, respectively. B, Plot of p_D versus p_{FA} , called an ROC curve. Different thresholds will correspond to different values of p_D and p_{FA} (dashed double arrows in A and B). C, Overall probability of error (see Equation 2), computed from the ROC curve in B. D, Probability of correct detection obtained from the spike trains of an amplitude-sensitive afferent neuron as a function of the number of spikes above spontaneous activity generated by the cell (circles). Note that the cell can discriminate with more than 90% accuracy increases of three spikes or more, corresponding to a 1% increase in firing rate. Different models that take into account only the mean firing rate (squares), the mean firing rate and the interspike interval distribution (diamonds), or in addition the joint properties of successive intervals (triangles) are unable to match the experimental performance. (Adapted from Ratnam and Nelson, 2000.)



Figure 3. *A*, Stimulus estimation is performed using a linear algorithm (see *B*) that is based on a comparison of the stimulus and its estimate aimed at minimizing the mean square error between the two (Equation 4). *B*, The linear algorithm consists in taking a spike train (left) and placing a waveform (right) around each spike. Linear superposition of these waveforms (bottom) yields the estimate. The waveform is chosen to minimize the mean square error between stimulus and estimate (see *A*). *C*, Estimation of a random amplitude modulation from the spike train of an amplitude sensitive afferent neuron in *Eigenmannia* (mean firing rate 314 spk/s). *D*, Same stimulus estimated from a Poisson spike train encoding the stimulus according to Equation 3 at the same mean firing rate as in *C*.